Forecasting with Bayesian non-parametric methods

Massimiliano MARCELLINO¹ and Michael PFARRHOFER²

(1) Bocconi University, IGIER & CEPR (2) University of Vienna & WU Vienna

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- This paper is part of a research project on the use of classical and Bayesian non-parametric approaches to handle parameter time-variation and non-linearities in econometric models, possibly of large dimension.
- >> Non-parametric approaches have a long tradition in statistics and econometrics, but up to a few years ago their empirical application was uncommon, mainly due to computational issues, particularly so for large models.
- They are typically less efficient but more robust than parametric methods, requiring fewer (though still some) assumptions.
- >> Earlier papers on estimation, then also forecasting and structural analysis.

Classical non-parametric approach (kernel based), relies on and extends work by Giraitis, Kapetanios and Yates:

- (2019) "Large Time-Varying Parameter VAR: A Non-Parametric Approach," with George Kapetanios and Fabrizio Venditti, Journal of Applied Econometrics, 34(7), 1027-1049.
- (2021) "Time-Varying Instrumental Variable Estimation," with Liudas Giraitis and George Kapetanios, Journal of Econometrics, 224(2), 394-415.
- (2022) "Estimation and inference in large heterogeneous panels with stochastic time-varying coefficients," with Yu Bai and George Kapetanios.
- (2023) "The time-varying 3PRF," with Yiannis Dendramis and George Kapetanios.
- (2023) "Time Varying IV-SVARs and the effects of monetary policy on financial variables," with Robin Braun and George Kapetanios.

Bayesian non-parametric approach relies on various methods "imported" from statistics: BART, GP, BNN:

- (2023) "Tail forecasting with multivariate Bayesian additive regression trees," with Todd Clark, Florian Huber, Gary Koop and Michael Pfarrhofer, International Economic Review, forthcoming.
- (2022) "Investigating growth at risk using a multi-country non-parametric quantile factor model," with Todd Clark, Florian Huber, Gary Koop and Michael Pfarrhofer, arXiv 2110.03411.
- (2022) "Forecasting US Inflation Using Bayesian Nonparametric Models," with Todd Clark, Florian Huber and Gary Koop, Cleveland FED WP WP 22-05.
- (2022) "Gaussian Process Vector Autoregressions and Macroeconomic Uncertainty," with Niko Hauzenberger, Florian Huber and Nico Petz, CEPR WP 17646.

- (202X) "Nonparametric methods for measuring asymmetries in monetary policy transmission," with Florian Huber, Michael Pfarrhofer and Anna Stelzer.
- (202X) "Unusual weather in unusual economic times," with Florian Huber, Tamás Krisztin and Leopold Ringwald.
- >> (202X) "Oil in the tails," with Christiane Baumeister and Florian Huber.
- (2023) "Enhanced Bayesian neural networks for macroeconomics and finance," with Niko Hauzenberger, Florian Huber and Karin Kleiber.

- In this paper we review specification and estimation of Bayesian nonparametric models for forecasting (possibly large sets of) macroeconomic and financial variables, focusing on Bayesian Additive Regression Trees (BART) and Gaussian Processes (GP). This involves introducing flexible specifications for both the conditional mean functions and variances.
- >> We then apply various versions of these models for point, density and tail forecasting using a real time dataset for the euro area (Banbura *et al.*, 2021).
- The performance is compared with that of several variants of Bayesian VARs to assess the relevance of accounting for non-standard, general forms of nonlinearities and parameter time variation.

Econometric framework

>> We work with general multivariate models of the form:

$$\boldsymbol{y}_t = F(\boldsymbol{x}_t) + \boldsymbol{\epsilon}_t \tag{1}$$

 y_t is an $n \times 1$ vector, and $x_t = (y'_{t-1}, \dots, y'_{t-p})'$ is $k = np \times 1$ collecting p lags

- ▶ $F(\mathbf{x}_t) = (f_1(\mathbf{x}_t), \dots, f_n(\mathbf{x}_t))'$ are (possibly unknown) conditional mean functions $f_i(\mathbf{x}_t) : \mathbb{R}^k \to \mathbb{R}$ for $i = 1, \dots, n$, such that $F(\mathbf{x}_t) : \mathbb{R}^k \to \mathbb{R}^n$
- > ϵ_t reflects the unpredictable component; it is specified such that we can estimate our model equation-by-equation
- >> Models will be distinguished with respect to how we treat the function $F(\mathbf{x}_t)$ and what we assume about the error term ϵ_t

Benchmark vector autoregression (VAR)

≫ The simplest case is to restrict $F(x_t)$ to linearity, i.e., $F(x_t) = A_t x_t$:

$$y_t = A_t x_t + \epsilon_t$$

 A_t are $n \times k$ (possibly time-varying) VAR coefficients

>> VAR: $F(\mathbf{x}_t) = A\mathbf{x}_t$, constant for all $t = 1, \ldots, T$,

>> TVP: $F(x_t) = A_t x_t$ combined with state equation for $a_t = \operatorname{vec}(A_t)$

$$\boldsymbol{a}_t = \boldsymbol{a}_{t-1} + \boldsymbol{\varepsilon}_t, \quad \boldsymbol{\varepsilon}_t \sim \mathcal{N}(\boldsymbol{0}_{nk}, \boldsymbol{\Theta})$$

with a diagonal matrix Θ collecting state innovation variances — these govern the amount of time-variation

Bayesian additive regression trees (BART)

- >> Sum-of-tree model introduced in Chipman et al. (2010)
- >> Equation-specific functions $f_i(\mathbf{x}_t)$ are approximated using BART:

$$f_i(\mathbf{x}_t) pprox \sum_{s=1}^{S} l_{is}(\mathbf{x}_t | \mathcal{T}_{is}, \boldsymbol{\mu}_{is})$$

 $l_{is}(\mathbf{x}_t | \mathcal{T}_{is}, \boldsymbol{\mu}_{is})$ are individual tree functions (explaining small fractions)

- > Tree structures \mathcal{T}_{is} and terminal nodes μ_{is}
- > BART approximates the function $f_i(x_t)$ summing over *S* trees
- ≫ A simple example with scalar dependent $y = (y_1, ..., y_T)'$, a single predictor $x = (x_1, ..., x_T)'$ and shocks $\epsilon = (\epsilon_1, ..., \epsilon_T)'$

Bayesian additive regression trees (BART)

>> Considering a single tree for full data matrices:

$$\boldsymbol{y} = l(\boldsymbol{x}|\mathcal{T}, \boldsymbol{\mu}) + \boldsymbol{\epsilon}, \quad E(\boldsymbol{y}|\boldsymbol{x}) = l(\boldsymbol{x}|\mathcal{T}, \boldsymbol{\mu}) = \sum_{k=1}^{\#\text{TN}} \mu_k \mathbb{I}(\boldsymbol{x} \in \mathcal{S}_k)$$

- **>>** The tree is defined by sets $\mathcal{T} = \{S_k\}_{k=1}^{\#\text{TN}}$
- ≫ Sets S_k formed by partitioning *x* via splitting rules: {*x* ≤ *c*} or {*x* > *c*}
- >> Values of the function over *t* are associated terminal nodes μ_k
- BART sums over many such trees, and we have many predictors in practice splitting rules (variables/thresholds) estimated alongside terminal nodes

Fitting data using a single regression tree



Fitting data using BART



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Gaussian process (GP) regression

GP prior on the conditional mean functions (see, e.g., Williams and Rasmussen, 2006):

 $f_i(\mathbf{x}_t) \sim \mathcal{GP}\left(0, \mathcal{K}_{\boldsymbol{\vartheta}_i}(\mathbf{x}_t, \mathbf{x}_t)\right)$

≫ Using $X = (x_1, ..., x_T)'$, this prior becomes a (finite) multivariate Gaussian:

$$f_i \sim \mathcal{N}\left(\mathbf{0}_T, \mathcal{K}_{\boldsymbol{artheta}_i}(\boldsymbol{X}, \boldsymbol{X}')
ight), \quad f_i = \left(f_i(\boldsymbol{x}_1), \dots, f_i(\boldsymbol{x}_T)
ight)'$$

- >> Kernel K_{∂i}(X, X') with typical (t, t̃) element K_{∂i}(x_t, x_{t̃})
 > Distance based, d_{t̃t} = ||x_t x_{t̃}||² capturing similarities in input space
 > Hyperparameters ∂_i = (ξ_i, l_i)' regulate properties of permitted functions
- >> We use a squared exponential Kernel (others are available)

$$\mathcal{K}_{\boldsymbol{artheta}_i}\left(\boldsymbol{x}_t, \boldsymbol{x}_{ ilde{t}}
ight) = \xi_i imes \exp\left(-l_i d_{t ilde{t}}/2
ight)$$

Gaussian process (GP) regression



Conditional variances

- >> Few common sources drive the reduced form shocks (i.e., primitive shocks)
- >> Variants of factor stochastic volatility (FSV,g Aguilar and West, 2000)

 $oldsymbol{\epsilon}_t = L \mathfrak{F}_t + oldsymbol{\eta}_t$

 \mathfrak{F}_t are $q \times 1$ latent factors linked to observed space by $n \times q$ loadings matrix L plus idiosyncratic noise $\eta_t = (\eta_{1t}, \dots, \eta_{nt})'$

>> We assume heteroskedastic factors

$$\mathfrak{F}_t \sim \mathcal{N}(\mathbf{0}_q, \mathbf{\Omega}_t), \quad \boldsymbol{\eta}_t \sim \mathcal{N}(\mathbf{0}_n, \boldsymbol{H}_t), \\ \mathbf{\Omega}_t = \operatorname{diag}\left(\exp(\omega_{1t}), \dots, \exp(\omega_{qt})\right), \quad \boldsymbol{H}_t = \operatorname{diag}\left(\exp(h_{1t}), \dots, \exp(h_{nt})\right)$$

Conditional variances

>> Stochastic volatility (SV) processes capturing dynamics of volatility

$$\omega_{it} = \phi_{i\omega}\omega_{it-1} + \varsigma_{i\omega}\xi_{it}, \quad \xi_{it} \sim \mathcal{N}(0,1), \quad \text{for } i = 1, \dots, q,$$

$$h_{jt} = \mu_{jh} + \phi_{jh}(h_{jt-1} - \mu_{jh}) + \varsigma_{jh}\xi_{jt}, \quad \xi_{jt} \sim \mathcal{N}(0,1), \quad \text{for } j = 1, \dots, n.$$

- >> Note that $\operatorname{Var}(\boldsymbol{\epsilon}_t) = \operatorname{Var}(\boldsymbol{L}\mathfrak{F}_t + \boldsymbol{\eta}_t) = \boldsymbol{L}\boldsymbol{\Omega}_t\boldsymbol{L}' + \boldsymbol{H}_t$
- >> Order-invariance of the multivariate system (see also Chan *et al.*, 2022)
- >> Conditionally independent equations i = 1, ..., n:

$$\tilde{y}_t = y_t - L\mathfrak{F}_t, \quad \tilde{y}_{it} = f_i(x_t) + \eta_{it}, \quad \eta_{it} \sim \mathcal{N}\left(0, \exp(h_{it})\right)$$

Summary of the models

>> General multivariate models of the form:

$$\boldsymbol{y}_t = F(\boldsymbol{x}_t) + \boldsymbol{L} \mathfrak{F}_t + \boldsymbol{\eta}_t, \quad \mathfrak{F}_t \sim \mathcal{N}(\boldsymbol{0}_q, \boldsymbol{\Omega}_t), \quad \boldsymbol{\eta}_t \sim \mathcal{N}(\boldsymbol{0}_n, \boldsymbol{H}_t)$$

>> We consider four options for $F(\mathbf{x}_t) = (f_1(\mathbf{x}_t), \dots, f_n(\mathbf{x}_t))'$

- 1. **Linear**/**TVP**: $F(x_t) = A_t x_t$, horseshoe shrinkage
- 2. **BART**: $f_i(\mathbf{x}_t) \approx \sum_{s=1}^{S} l_{is}(\mathbf{x}_t | \mathcal{T}_{is}, \boldsymbol{\mu}_{is})$
- 3. **GP**: $f_i(\mathbf{x}_t) \sim \mathcal{GP}(0, \mathcal{K}_{\boldsymbol{\theta}_i}(\mathbf{x}_t, \mathbf{x}_t))$
- >> Homoskedastic by assuming $H_t = H$ and $\Omega_t = I_q$, labeled "hom"
- >> Heteroskedastic case (stochastic volatility) indicated by "sv," e.g., "Linear sv" is a standard BVAR with SV

How do the competitors fit data?





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Sketch of the estimation algorithm

Standard MCMC algorithm (Gibbs sampling, Metropolis-Hastings steps); conditional updates for ...

- 1. $F(x_t)$ equation-by-equation conditional on the factors;
- 2. any hyperparameters related to $F(x_t)$, e.g., shrinkage for linear/TVP, Kernel hyperparameters for GP, etc.;
- 3. *L* and \mathfrak{F}_t conditional on each other, \mathfrak{F}_t in one block;
- 4. log-volatility processes in H_t and Ω_t conditional on η_t and f_t ;
- 5. missing values in y_t due to the release calendar
- 6. iterative multi-step-ahead forecasts via Monte Carlo to account for all sources of uncertainty, yields y_{T+h}

Details on step 1/2: $F(x_t)$ for **BVAR/TVP**

- >> Global-local shrinkage on the elements in A; or in non-centered TVP parameterization, on initial state A_0 and square root of the state innovation variances $\sqrt{\Theta}$
- >> For some generic coefficient β_i , this prior is given by:

$$\beta_j \sim \mathcal{N}(0, \lambda_j^2 \tau^2), \quad \lambda_j \sim \mathcal{C}^+(0, 1), \quad \tau \sim \mathcal{C}^+(0, 1)$$

- Coefficients and state innovation variances can be sampled equation-by-equation (as can the TVPs via standard methods)
 - > Conditionally conjugate posteriors for all required quantities
 - > Global/local shrinkage factors can be updated in one block

Details on step 1: $F(x_t)$ **for BART**

- >> Tree generating stochastic process that serves as a prior
 - > Probability that a node at depth d = 1, ..., is nonterminal: $\alpha/(1+d)^{\beta}$ for $\alpha \in (0, 1)$ and $\beta \in \mathbb{R}^+$ (we use default values of Chipman *et al.*, 2010)
 - > Discrete uniform prior on variables that appear in splitting rules
 - > Discrete uniform prior (on range of splitting variable) for thresholds
- >> Independent Gaussian priors on the terminal node parameters for tree s = 1, ..., S, in equation i = 1, ..., n:

$$\mu_{is,k} \sim \mathcal{N}(0,\phi_i), \text{ for } k = 1,\ldots, \# \mathrm{TN}$$

>> Informativeness of this prior is set in a data-based fashion:

$$\sqrt{\phi_i} = rac{\max(oldsymbol{y}_i) - \min(oldsymbol{y}_i)}{2\gamma\sqrt{S}}$$

Details on step 1: $F(x_t)$ **for BART**

- >> Individual trees sampled conditional on remaining S 1 trees, marginal of the terminal node parameters μ_{is} , see Chipman *et al.* (2010)
 - > Keeps dimensionality of the problem fixed
 - > Metropolis-Hastings updates of trees, with four transitions:
 - (1) grow or (2) prune tree, (3) change splitting rule, (4) swap splitting rule

>> Gaussian posteriors of terminal nodes (conditional on tree structures)

Details on step 1/2: $F(x_t)$ for **GP**

>> Conditional on the FSV-related quantities, we have:

$$ilde{y}_i = f_i + \eta_i, \quad f_i \sim \mathcal{N}(\mathbf{0}_T, \mathcal{K}_{\boldsymbol{artheta}_i}), \quad \eta_i \sim \mathcal{N}(\mathbf{0}_T, H_i)$$

where all quantities are for equation i = 1, ..., n, and stacked over t, and $H_i = \text{diag}(\exp(h_{i1}), ..., \exp(h_{iT}))$

>> Posterior of $f_i | \tilde{y}_i \sim \mathcal{N}(\overline{f_i}, \overline{V_i})$ is a multivariate Gaussian

$$\overline{f_i} = \mathcal{K}_{\boldsymbol{\vartheta}_i} (\mathcal{K}_{\boldsymbol{\vartheta}_i} + \boldsymbol{H}_i)^{-1} \tilde{\boldsymbol{y}}_i$$
$$\overline{\boldsymbol{V}_i} = \mathcal{K}_{\boldsymbol{\vartheta}_i} - \mathcal{K}_{\boldsymbol{\vartheta}_i} (\mathcal{K}_{\boldsymbol{\vartheta}_i} + \boldsymbol{H}_i)^{-1} \mathcal{K}_{\boldsymbol{\vartheta}_i}$$

>> Predictive distribution takes a similar form

Details on step 1/2: $F(x_t)$ for **GP**

- >> Conditional likelihood $\tilde{y}_i \sim \mathcal{N}(\mathbf{0}_T, \mathcal{K}_{\vartheta_i} + H_i)$ is used to update hyperparameters $\vartheta_i = (\xi_i, h_i)'$
- **>>** Metropolis-Hastings updates for $\xi_i \sim \mathcal{G}(a_{\xi}, b_{\xi})$ and $l_i \sim \mathcal{G}(a_l, b_l)$
 - > Specific to equation *i*, i.e., flexibility regarding type of dependent
 - > Asymmetric log-normal proposals, straightforward acceptance probabilities

Real time forecasts for the EA

- >> Series start in 1980Q2 and we use p = 4 lags with small (n = 3) information sets
- >> History of vintages from 2001Q1 to 2021Q3
 - > First evaluation period 2001Q2
 - Final observation 2021Q3
- >> Evaluated using final vintage data
- Target variables: QoQ GDP growth (GDP), QoQ headline inflation (HICP), unemployment rate (UNR, in differences)

- >> Conditional nowcast scheme to sample ragged edges online
- >>> Benchmark: Linear BVAR with homoskedastic errors



Real time vintages (dataset and size of revisions)

Predictive loss functions

- >> Let $y_{i,t+h}^{(r)}$ be the realization and $y_{i,t+h}^{(fp)}$ is the *p*th quantile of the predictive distribution
- >> Quantile score (QS) as in Giacomini and Komunjer (2005)

$$QS(p)_{i,t+h} = \left(y_{i,t+h}^{(r)} - y_{i,t+h}^{(fp)}\right) \times \left(p - \mathbb{I}\left(y_{i,t+h}^{(r)} < y_{i,t+h}^{(fp)}\right)\right),$$

e.g., QS(0.5) is the (half) mean absolute error (point forecast metric)

Quantile-weighted continuous ranked probability score (CRPS), as in Gneiting and Ranjan (2011)

$$\operatorname{CRPS}_{i,t+h}(\mathfrak{w}_p) = \int_0^1 \mathfrak{w}_p \operatorname{QS}(p)_{i,t+h} \mathrm{d}p,$$

>> Weights w_p to target different parts of the distribution

Estimation times

Linear-hom takes about 30 seconds for 10k posterior and predictive draws (Macbook Air M1, 2020)

Specification	Relative time
Linear hom	1.00
Linear sv	1.09
BART hom	1.18
BART sv	1.28
TVP sv	1.84
GP hom	2.39
GP sv	2.49

Forecast results

h = 1

None								Left					Right			QS50					
	TVP SV -	0.92	0.99	0.88	1.00	0.86	0.98	1.02	0.96	1.01	0.95	0.85	0.95	0.80	0.98	0.79	0.92	1.00	0.87	0.99	0.87
	Linear SV	0.82	0.98	0.72	1.01	0.68	0.86	1.02	0.77	1.03	0.68	0.78	0.95	0.69	0.98	0.69	0.80	0.99	0.68	1.00	0.67
Р	GP SV -	0.83	0.99	0.74	0.99	0.72	0.86	1.00	0.78	0.99	0.71	0.80	0.98	0.70	0.97	0.72	0.81	0.98	0.71	0.98	0.70
G	GP hom -	0.82	0.99	0.72	0.95	0.72	0.85	1.01	0.76	0.96	0.72	0.79	0.97	0.70	0.94	0.73	0.81	0.98	0.71	0.94	0.73
	BART SV -	0.83	1.00	0.74	1.01	0.71	0.87	1.02	0.78	1.02	0.71	0.80	0.99	0.70	0.99	0.72	0.81	0.99	0.70	1.00	0.68
	BART hom -	0.94	1.00	0.90	0.99	0.90	0.94	1.00	0.90	0.99	0.88	0.94	1.00	0.91	0.99	0.92	0.93	0.99	0.89	0.99	0.89
	TVP SV -	0.99	1.02	0.90	1.00	0.99	1.01	1.03	0.94	1.01	1.02	0.98	1.01	0.87	1.00	0.97	0.99	1.00	0.91	0.99	0.99
	Linear SV	0.99	1.00	0.92	1.00	0.98	1.00	1.01	0.93	1.00	1.00	0.97	0.99	0.90	1.00	0.97	0.98	0.99	0.93	1.00	0.98
6	GP SV -	0.92	1.00	0.60	0.99	0.90	0.93	0.98	0.70	0.97	0.92	0.91	1.03	0.50	1.02	0.88	0.92	0.97	0.66	0.98	0.90
ĭ	GP hom -	0.91	0.99	0.59	0.99	0.89	0.93	0.99	0.67	0.99	0.91	0.90	1.01	0.50	1.00	0.87	0.91	0.96	0.66	0.98	0.89
	BART SV -	0.97	1.03	0.72	1.02	0.95	0.98	1.02	0.78	1.00	0.97	0.96	1.04	0.67	1.04	0.94	0.95	1.00	0.77	1.03	0.93
	BART hom -	0.97	1.02	0.76	1.01	0.95	0.96	1.00	0.78	0.99	0.96	0.97	1.04	0.73	1.04	0.96	0.97	1.01	0.80	1.01	0.96
	TVP SV	0.95	0.99	0.82	0.97	0.94	0.93	1.00	0.75	0.97	0.92	0.96	0.99	0.89	0.97	0.96	0.93	0.97	0.78	0.96	0.91
	Linear SV	0.98	1.03	0.83	0.98	0.97	0.97	1.04	0.76	0.97	0.97	0.99	1.02	0.89	0.99	0.98	0.96	1.01	0.80	0.97	0.96
2	GP SV -	0.91	0.94	0.81	0.85	0.93	0.92	0.98	0.72	0.87	0.94	0.90	0.91	0.88	0.84	0.93	0.89	0.93	0.78	0.84	0.92
S	GP hom -	0.90	0.94	0.78	0.83	0.93	0.91	0.97	0.71	0.84	0.93	0.90	0.92	0.85	0.83	0.93	0.89	0.92	0.78	0.81	0.92
	BART SV	0.89	0.90	0.87	0.87	0.91	0.91	0.93	0.83	0.87	0.92	0.89	0.88	0.91	0.87	0.90	0.87	0.88	0.84	0.86	0.88
	BART hom -	0.92	0.90	0.97	0.87	0.94	0.94	0.92	0.99	0.88	0.96	0.91	0.89	0.96	0.87	0.93	0.90	0.89	0.94	0.87	0.92
		Full -	Pre Covid	Post Covid ⁻	Recession ⁻	Expansion -	Full	Pre Covid	Post Covid ⁻	Recession -	Expansion ⁻	Full -	Pre Covid	Post Covid ⁻	Recession -	Expansion ⁻	Full -	Pre Covid ⁻	Post Covid	Recession -	Expansion -

Forecast results

h = 4

				None					Left					Right					QS50	1	
	TVP SV	0.99	0.98	1.00	0.98	1.00	1.00	1.01	1.00	0.99	1.02	0.98	0.94	1.01	0.96	0.99	0.99	0.99	0.99	0.97	1.01
	Linear SV	0.99	0.97	1.01	0.99	0.99	1.00	1.00	1.02	1.00	1.01	0.98	0.94	1.01	0.97	0.99	0.99	0.98	1.00	0.98	1.00
	ት GP SV ·	0.99	0.98	1.00	0.97	1.00	0.99	0.99	1.00	0.96	1.03	0.99	0.97	1.00	0.97	0.99	0.98	0.97	0.99	0.97	0.99
Ċ	י GP hom י	- 0.98	0.98	0.97	0.94	1.00	0.98	1.01	0.95	0.93	1.03	0.98	0.96	0.99	0.96	0.98	0.97	0.97	0.98	0.95	0.98
	BART SV	- 1.00	0.99	1.01	1.00	1.00	1.02	1.01	1.03	1.01	1.03	0.99	0.96	1.01	0.99	0.99	0.99	0.98	1.00	0.99	0.99
	BART hom	- 1.00	0.99	1.00	0.99	1.00	1.00	1.00	1.00	0.99	1.01	0.99	0.98	1.01	0.99	0.99	0.99	0.98	1.00	0.99	0.99
	TVP SV	1.01	1.01	0.99	1.00	1.01	1.02	1.02	0.99	0.99	1.03	0.99	1.00	0.99	1.01	0.99	1.00	1.01	0.99	1.01	1.00
	Linear SV	- 1.00	0.99	1.00	1.00	0.99	1.00	1.00	1.01	0.99	1.00	0.99	0.99	1.00	1.01	0.98	0.99	0.99	1.00	1.00	0.99
1	GP SV ·	0.93	0.94	0.82	0.95	0.92	0.92	0.92	0.85	0.93	0.91	0.94	0.98	0.78	0.98	0.94	0.90	0.91	0.86	0.95	0.89
	GP hom	0.90	0.92	0.81	0.93	0.89	0.89	0.90	0.84	0.92	0.89	0.91	0.94	0.78	0.95	0.90	0.89	0.89	0.86	0.91	0.88
	BART SV	0.93	0.93	0.91	0.89	0.94	0.93	0.93	0.93	0.89	0.94	0.93	0.94	0.90	0.88	0.95	0.92	0.92	0.92	0.90	0.93
	BART hom	0.94	0.94	0.91	0.91	0.94	0.93	0.94	0.91	0.91	0.94	0.94	0.95	0.90	0.92	0.95	0.93	0.93	0.92	0.90	0.94
	TVP SV	1.00	1.01	0.95	0.99	1.01	1.00	1.02	0.91	1.01	1.00	1.01	1.01	0.98	0.97	1.02	1.00	1.01	0.94	1.00	1.00
	Linear SV	1.03	1.03	1.03	0.97	1.05	1.04	1.04	1.06	0.99	1.07	1.01	1.01	1.01	0.96	1.04	1.03	1.03	1.03	0.99	1.05
9	≚ GP SV	0.97	0.96	1.03	0.91	1.01	1.00	0.99	1.07	0.94	1.03	0.95	0.94	1.02	0.88	0.99	0.98	0.97	1.01	0.94	1.00
1	GP hom	1.01	1.00	1.08	0.96	1.04	1.04	1.02	1.13	0.97	1.07	0.99	0.98	1.05	0.96	1.02	1.01	1.00	1.09	0.97	1.03
	BART SV	0.99	0.98	1.03	0.93	1.02	1.01	1.00	1.07	0.94	1.04	0.97	0.97	1.01	0.93	1.00	0.99	0.99	1.00	0.94	1.01
	BART hom	1.00	0.99	1.07	0.95	1.03	1.02	1.00	1.11	0.94	1.05	0.99	0.98	1.04	0.95	1.01	1.01	1.00	1.07	0.96	1.03
		Full	Pre Covid	Post Covid ⁻	Recession -	Expansion ⁻	Full	Pre Covid	Post Covid	Recession -	Expansion ⁻	- In1	Pre Covid	Post Covid	Recession	Expansion ⁻	- In1	Pre Covid	Post Covid	Recession	Expansion

Forecast results

h = 8

None						Left							Right			QS50					
	TVP SV	0.99	0.97	0.99	0.98	1.00	0.99	0.98	0.99	0.97	1.01	0.99	0.96	1.00	0.98	0.99	0.98	0.98	0.99	0.98	0.99
	Linear SV	- 0.98	0.96	1.00	0.98	0.99	0.99	0.96	1.01	0.98	0.99	0.98	0.96	1.00	0.98	0.98	0.98	0.97	0.99	0.98	0.98
	片 GP SV ·	- 0.99	0.98	1.00	0.98	1.01	0.99	0.99	1.00	0.97	1.04	0.99	0.99	1.00	0.99	1.00	0.99	0.98	0.99	0.99	0.99
Ċ	ច GP hom ·	- 0.99	0.99	0.99	0.98	1.00	0.99	1.00	0.98	0.97	1.03	0.99	0.98	1.00	0.99	0.99	0.99	0.99	0.99	0.99	0.99
	BART SV	- 0.99	0.97	1.01	0.99	1.00	1.00	0.98	1.01	0.98	1.03	0.99	0.96	1.01	0.99	0.99	0.99	0.98	1.00	0.99	0.99
	BART hom	- 0.99	0.98	1.00	0.99	0.99	0.99	0.99	1.00	0.99	1.00	0.99	0.97	1.00	0.99	0.99	0.99	0.98	1.00	0.99	0.99
	TVP SV	- 0.99	0.99	0.99	0.99	0.99	1.00	1.00	0.97	0.98	1.00	0.99	0.98	1.01	0.99	0.99	0.99	0.99	1.00	1.00	0.99
	Linear SV	1.01	1.01	1.01	1.03	1.00	1.01	1.01	1.01	1.04	1.01	1.00	1.00	1.01	1.03	0.99	1.01	1.01	1.01	1.03	1.00
1	GP SV ·	0.93	0.92	1.00	1.00	0.92	0.92	0.91	0.98	0.99	0.90	0.96	0.95	1.01	1.01	0.95	0.91	0.89	1.00	0.96	0.89
	GP hom	0.92	0.91	0.97	0.97	0.91	0.91	0.91	0.91	0.96	0.89	0.94	0.92	1.02	0.98	0.93	0.90	0.88	0.98	0.94	0.89
	BART SV	0.93	0.92	0.98	1.00	0.92	0.93	0.93	0.95	1.01	0.91	0.95	0.93	1.01	1.00	0.94	0.92	0.90	0.97	0.95	0.91
	BART hom	0.94	0.93	0.99	0.99	0.93	0.94	0.94	0.95	1.01	0.92	0.94	0.93	1.02	0.98	0.94	0.93	0.92	0.99	0.97	0.92
	TVP SV	- 0.99	0.99	0.99	0.98	0.99	1.00	1.00	1.00	1.04	0.98	0.98	0.98	0.98	0.93	1.00	0.99	0.99	0.99	1.01	0.98
	Linear SV	- 0.99	0.98	1.01	0.95	1.01	1.00	0.99	1.02	1.00	1.00	0.97	0.96	1.01	0.91	1.01	1.00	1.00	1.02	0.98	1.02
(≚ GP SV ·	- 1.00	1.00	0.99	0.87	1.07	1.03	1.03	1.01	0.92	1.08	0.97	0.97	0.97	0.82	1.06	1.02	1.02	0.98	0.92	1.07
	GP hom	1.02	1.03	0.98	0.92	1.07	1.05	1.05	1.02	0.96	1.09	1.00	1.01	0.94	0.89	1.06	1.04	1.05	1.00	0.97	1.07
	BART SV	1.01	1.01	1.02	0.89	1.08	1.05	1.05	1.03	0.92	1.11	0.98	0.98	1.01	0.85	1.06	1.02	1.02	1.01	0.92	1.07
	BART hom	1.03	1.03	1.02	0.91	1.09	1.06	1.06	1.05	0.93	1.12	1.00	1.00	0.99	0.90	1.06	1.03	1.03	1.02	0.93	1.08
		Full -	Pre Covid ⁻	Post Covid ⁻	Recession ⁻	Expansion ⁻	Full	Pre Covid	Post Covid ⁻	Recession -	Expansion ⁻	Full -	Pre Covid	Post Covid ⁻	Recession -	Expansion ⁻	Full	Pre Covid	Post Covid -	Recession -	Expansion ⁻

Running window (8 quarters) h = 1



Model — BART SV — GP SV — Linear SV — TVP SV

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Running window (8 quarters)h = 4



Model — BART SV — GP SV — Linear SV — TVP SV

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Running window (8 quarters) h = 8



Model — BART SV — GP SV — Linear SV — TVP SV

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Conclusions

- In this paper we review specification and estimation of Bayesian nonparametric models for forecasting (possibly large sets of) macroeconomic and financial variables, focusing BART and GP, possibly with SV.
- >> We apply various versions of these models for point, density and tail forecasting using a real time dataset for the euro area (Banbura *et al.*, 2021).
- The performance is compared with that of several variants of Bayesian VARs to assess the relevance of accounting for non-standard, general forms of nonlinearities and parameter time variation.

Conclusions

- For GDP, BVAR-SV overall best, except during recessions and in the left tail, where GP-hom best, with gains shrinking in h.
- For HICP, GP-hom overall best, with larger gains post-Covid and for h=1, but still present for other periods and horizons.
- For UNR, BART overall best, GP-hom during recessions and in the right tail (UNR up).
- For GP, and partly BART, often little or no gains from SV, much less than for BVAR.

>> GP overall quite promising for forecasting during problematic periods.